WorkEZTM

UncagedErgomomics.com

Introducing WorkEZ

Each joint is measured in 15° increments. Joints lock in place every 15°.

To operate a joint, depress the button and rotate the leg to the desired angle

Once the button is depressed, joints rotate in a complete circle or 360°.

The joint is locked when the button is extended. Only use WorkEZ when all joints are locked.



Depress the button to adjust the leg.



An extended button means the joint is locked.



When adjusting be wary of your fingers

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WorkEZ Professional





Completely adjustable to fit your physique and environment, WorkEZ Professional is competent as a desk-based stand and its sturdy design enhances utility on softer surfaces (beds, recliners, couches).

Guidelines

Max load is 13 lbs.

Joints must be locked (extended) before use. Before use, ensure that:

All joints are locked (extended)

The plattform is level

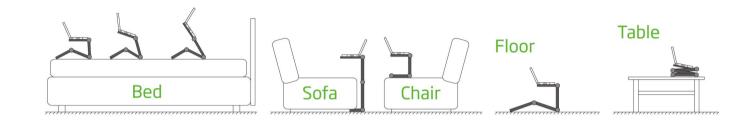
Both legs are adjusted identically & evenly

WorkEZ is stable

The platform weight is centered over the bottom leg

Tip: If WorkEZ tends to tip forward or backwards, rotate the bottom leg 180°.

Simplify life with 1 multi purpose stand



Disclaimer:

Buyer accepts full liability for any injury or loss to themselves, their property, and anyone else at any time and from any cause while using this product.

Buyer expressly releases Uncaged Ergomomics and its agents from any liability for such loss or injury. In no event shall Uncaged Ergonomics or its agents be liable for any direct, indirect, punitive, incidental, damages or injury whatsoever arising out of or connected with the use or misuse of its products.

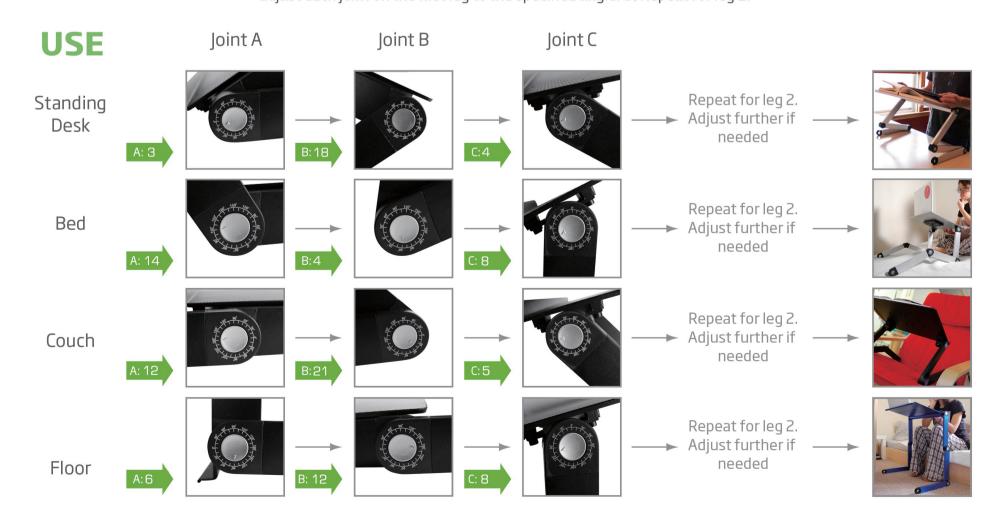


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How To Set Up:

1. Decide where you want to use WorkEZ . **2.** Follow this quick guide and adjust each joint on the first leg to the specified angle. **3.** Repeat for leg 2.



Customizing WorkEZ:

Simultaneously pressing the same joint on each leg lets you quickly and evenly adjust the platform angle or height

To Fold WorkEZ:

1. Fold Joint C to 0° **2.** Fold Joint B to 0° **3.** Fold Joint A to 0° **4.** Repeat for leg 2



